



# Temporally Aware Densefication for Dynamic 3D Gaussian Splatting

Vikram Sandu · Mayurdeep Pathak · Rajiv Soundararajan

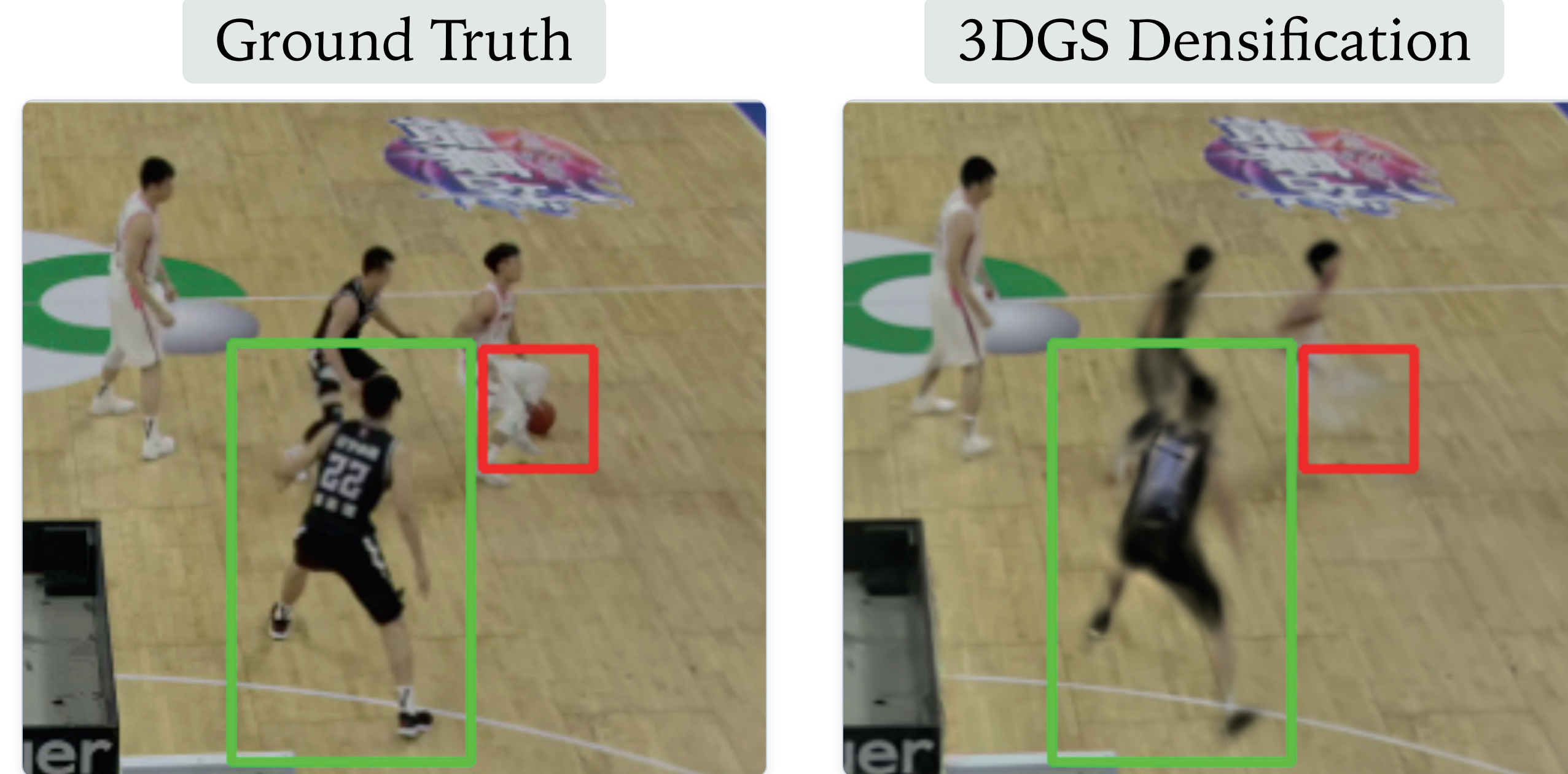
Indian Institute of Science, Bengaluru, India



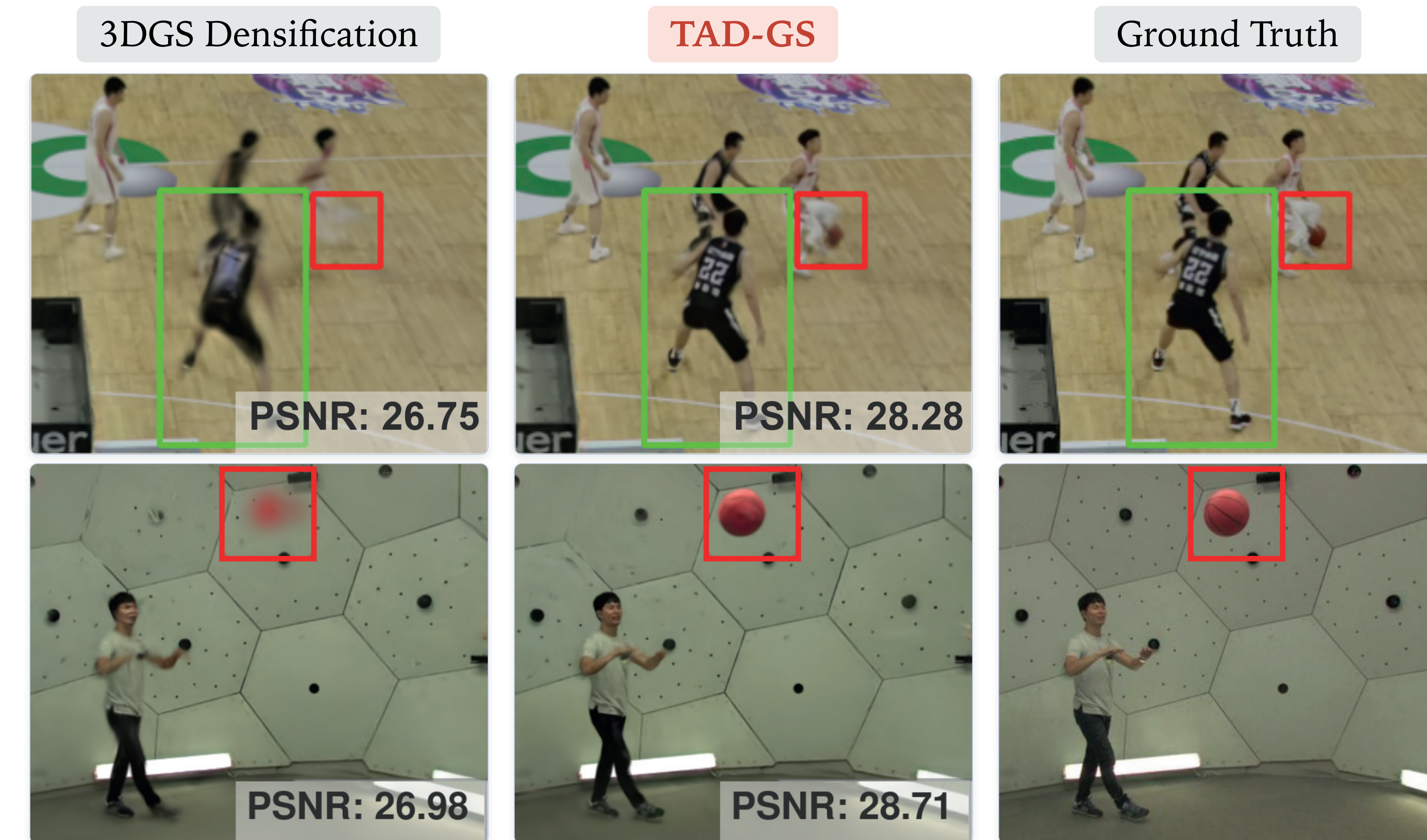
ECCV 2026 | MALMÖ | SEPT 8-12

## 1. Densefication in Dynamic 3DGS

- Dynamic 3DGS methods still inherit **static 3DGS Densefication**, leading to **sparse gradient** supervision and **blurry reconstructions** in **moving regions**.



## 4. Temporally Aware Densefication



## 2. Analyzing Densefication for Dynamic Gaussian

- Densification criterion:** a Gaussian is densified if its averaged positional gradient  $\bar{g}$ , accumulated over  $N$  iterations, exceeds a pre-defined threshold  $\tau_{\text{pos}}$ .
- Dynamic Gaussians typically have a **shorter temporal lifespan** to represent **complex motion**. For a dynamic Gaussian, the gradient signal  $\bar{g}$  decomposes as:

$$\bar{g}_i = \frac{1}{N} \sum_{t \in \text{visible}} g_i(t) + \frac{1}{N} \sum_{t \notin \text{visible}} g_i(t)$$

$\downarrow$  **Vanishes** (small numerator, large denominator)       $\downarrow$  **Vanishes** (not visible)

$\bar{g}_i$  rarely exceeds  $\tau_{\text{pos}}$ , and dynamic Gaussians remain un-densified.

## 3. Prior Work on Dynamic Densefication

|               | Visibility-aware gradient accumulation | Lifespan-adaptive densification threshold | Enhanced local motion modelling |
|---------------|----------------------------------------|-------------------------------------------|---------------------------------|
| SaRO-GS       | ✗                                      | ✓                                         | ✗                               |
| Anchored-4DGS | ✗                                      | ✓                                         | ✗                               |
| Ours          | ✓                                      | ✓                                         | ✓                               |

**Our Proposed Solution:** We redesign densification criterion based on **Gaussian visibility** and **temporal lifespan**, also enhancing **local motion modeling** for effective densification of dynamic Gaussians.

## TAD-GS (Ours)

### Densification Criterion

$$\frac{\sum_{t \in N} \sigma_i(t) g_i(t)}{\sum_{t \in N} \sigma_i(t)}$$

**Visibility Aware Densefication (VAD)**

- Visibility-weighted gradient accumulation
- Avoids gradient dilution** for dynamic Gaussians

$\sigma_i(t)$ : visibility

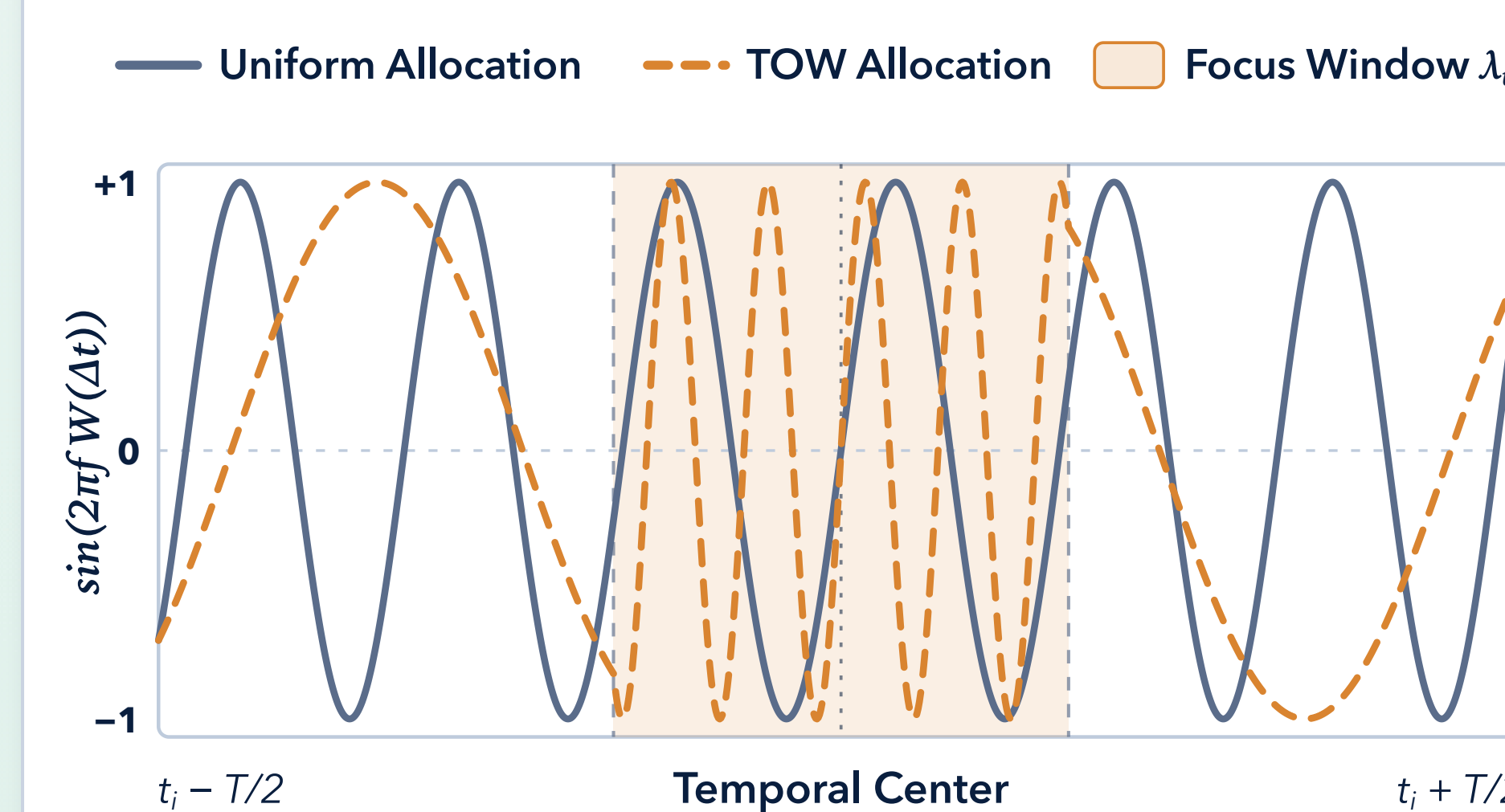
$$\tau_{\text{pos}} \cdot \left( \frac{1}{1 + \beta(1 - \bar{\psi}_i)} \right)^\alpha$$

**Temporally Adaptive Thresholding (TAT)**

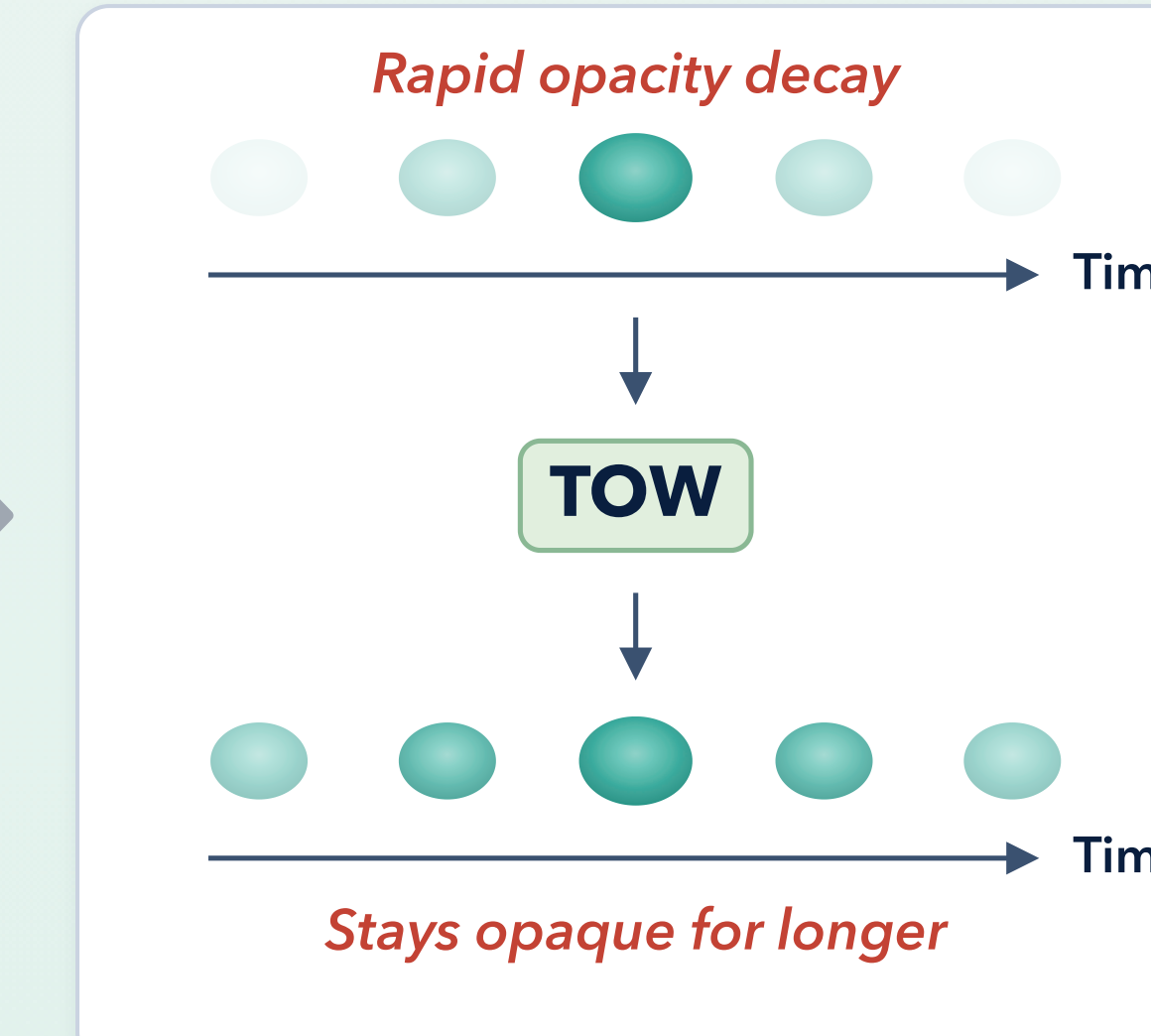
- Lifespan-aware thresholding
- Relaxes threshold bar** for dynamic Gaussians

$\bar{\psi}_i$ : temporal lifespan

### Temporal Offset Warping (TOW)

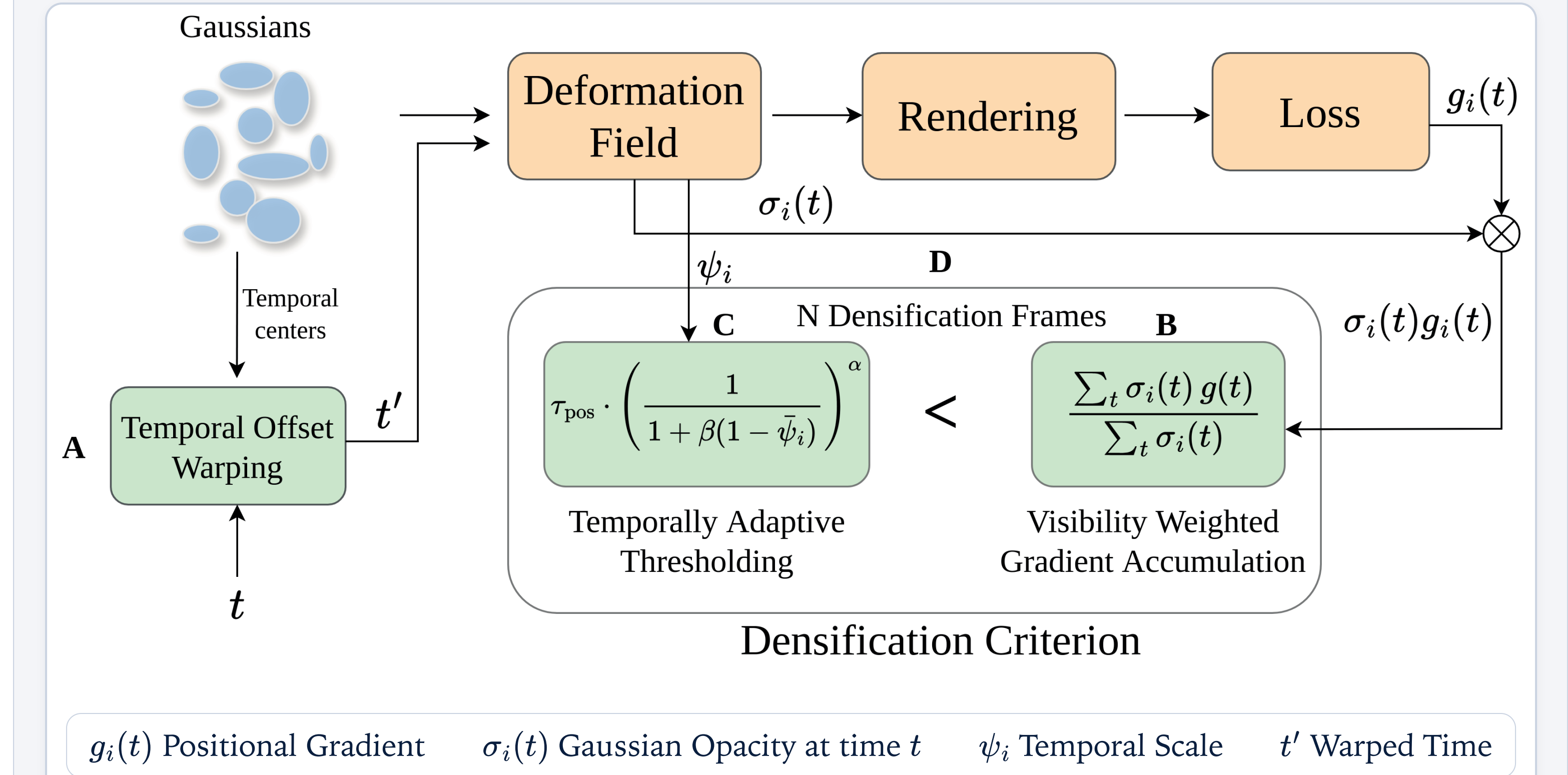


- Stretches time near center, shrinks it farther away
- Enhances Fourier-basis deformation modelling



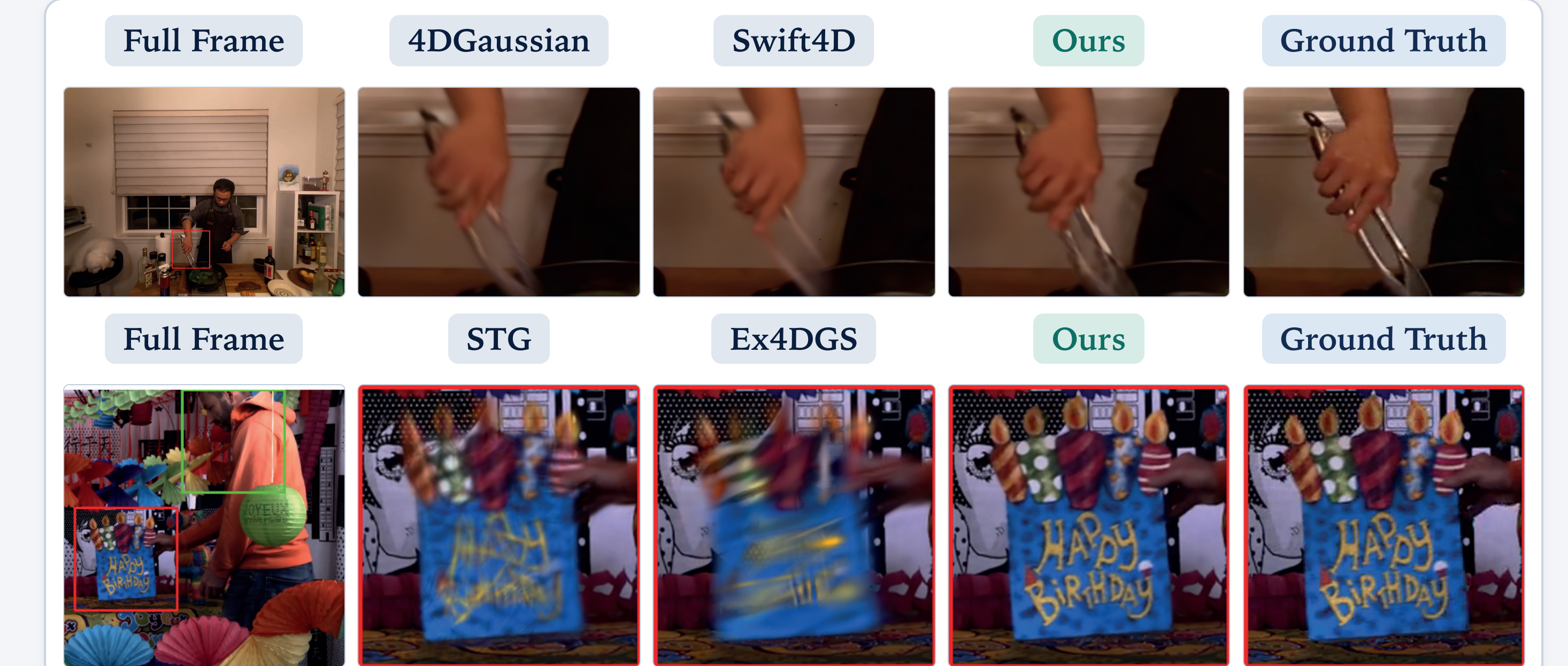
- Improves local motion modelling
- Increases Gaussian lifespan
- Improves gradient accumulation of dynamic Gaussians

## 5. TAD-GS Pipeline

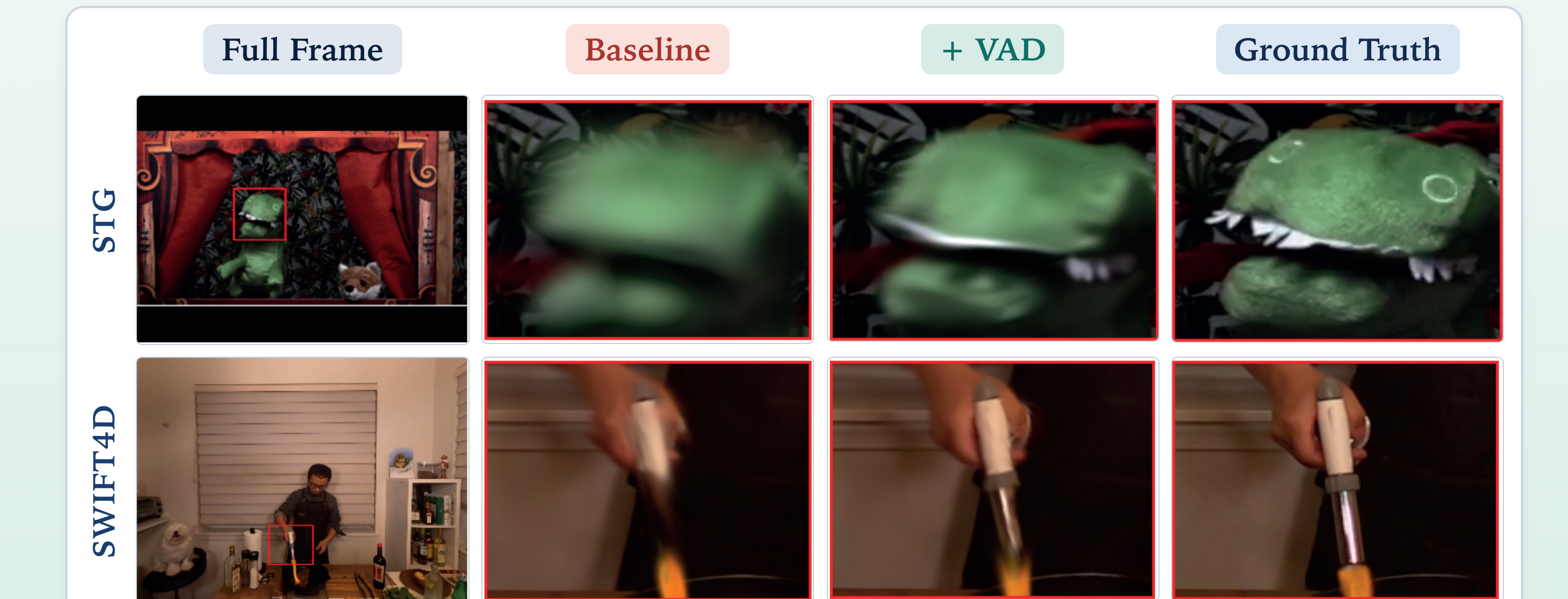


## 6. Results

|            | Neural 3D Video |                   |                   | Interdigital    |                   |                   |
|------------|-----------------|-------------------|-------------------|-----------------|-------------------|-------------------|
| Method     | PSNR $\uparrow$ | M-PSNR $\uparrow$ | M-SSIM $\uparrow$ | PSNR $\uparrow$ | M-PSNR $\uparrow$ | M-SSIM $\uparrow$ |
| 4DGaussian | 31.21           | 22.67             | 0.784             | 26.74           | 18.09             | 0.520             |
| STG        | 31.40           | 22.61             | 0.792             | 33.45           | 27.14             | 0.860             |
| Ex4DGS     | 31.45           | 23.40             | 0.814             | 32.44           | 26.15             | 0.844             |
| Swift4D    | 32.12           | 23.74             | 0.835             | 31.62           | 23.01             | 0.741             |
| Ours       | 32.42           | 24.68             | 0.863             | 34.14           | 28.87             | 0.901             |



VAD module can be easily plugged into any method to improve dynamic reconstruction.



**Acknowledgements:** supported in part by a grant from Anusandhan National Research Foundation, India (ANRF/ARG/2025/002993/ENS) and the Kotak IISc AI-ML Center.